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HYDROJET FOR WATERCRAFT

The present invention pertains to a hydrojet for watercraft.

Hydrojets, which are preferably arranged on the bow side in the bottom area, have proved to be successful for improving maneuverability especially in watercraft used in shallow waters (e.g., in inland waters with varying water levels). Such hydrojets, also called bow jet units, comprise a housing, which can be installed in the bottom of the particular watercraft and which contains at least one propeller (or a pump impeller), which introduces energy into the water fed in via a bottom-side housing intake and releases it [the water], for example, via an elbow and channels in their direction, or steers it all round through at least one discharge opening, which is flush with the bottom and can usually be pivoted by 360° under the bottom of the boat.

The axis of rotation of the propeller or of the pump impeller extends either in the horizontal direction or in the vertical direction in prior-art hydrojets.

In case of vertical arrangement of the propeller, i.e., rotation around a horizontal transverse axis in a cross jet tunnel, it shall be borne in mind that the water line should be about half the propeller diameter above the vertex of the tunnel to avoid the inrush of air and the drop in thrust caused thereby. This leads to the drawback that the watercraft in question has a relatively great draft and requires a corresponding depth of the shipping channel in order to be able to manoeuvre without

risk and efficiently.

Besides this, hydrojets with vertical arrangement of the propeller are also known, which have a bottom intake according to the principle of usual axial jets in order to reduce the draft. Because the suction behavior of axial-flow pumps allows a limited emersion of the propeller blades only, a draft ratio that depends on the function is to be ensured.

Even though hydrojets with vertically directed axis of rotation require a relatively small draft for air-free operation for the propeller (or pump impeller) arranged horizontally above a bottom intake, they do have, among other things, the drawback that in case of shallow depth of water (i.e., at less than, e.g., 50 cm of water under the keel), such drives generate a strong wake due to the suction effect directed directly toward the bottom, which wake increases the resistance of the boat and compromises the development of thrust or lets it collapse altogether when increased amounts of foreign bodies sucked in clog the protective grid, which is usually present. Furthermore, the risk for damage increases, because small foreign bodies can pass through the protective grid like a sieve and can increasingly enter between the blades.

In addition, it was found that in case of hydrojets with vertically directed axis of rotation of the propeller, the flow to be deflected into the vertical suction area begins to be broken down beginning from a certain velocity of travel with increasing speed, which will then lead to a drastic drop in thrust.

For driving via a horizontally arranged motor, hydrojets with vertical axis of rotation of the

propeller require an angular gear of their own. For driving by means of internal combustion engines, a marine reversing gear, which as a second gear increases the mechanical losses and the cost of the unit, is also necessary for coupling and changing over the direction of rotation (for example, for flushing the protective grid).

5 The basic object of the present invention is to propose a hydrojet that is as simple as possible and can be manufactured at a low cost, with an axial-flow pump, for watercraft, especially for displacement-type watercraft, which generates an efficient thrust with optimized incoming flow during manoeuvring and with increasing speed and has better shallow water properties than the prior-art bow jet plants and can be welded (or laminated) into the bottom of a watercraft as a
10 compact drive unit.

This object is accomplished according to the present invention by the features of claim 1. Other, especially advantageous embodiments of the present invention are disclosed in the subclaims.

The present invention is based essentially on the idea of arranging the propeller shaft of the hydrojet on the delivery side of the particular axial-flow pump in a commercially available 90° pipe bend
15 such that the axis of rotation of the propeller is not vertical or horizontal but has a slope angle α of 20° to 50°, preferably between 25° and 40°, in relation to the bottom plate as the horizontal base, and a discharge housing section is attached at the other, obliquely downwardly pointing end of the pipe bend and is provided with a rotatable bottom deflection grid in order to steer the discharge jet and hence the propeller thrust all round in all directions under the bottom of the hydrojet.

Major advantages are achieved due to this measure concerning

- design and manufacture,
- the guiding of the flow and the development of the thrust,
- the speed and the draft,
- the installation of alternative drive motors, and
- the possibilities of installation in the watercraft models.

Due to the propeller being inclined toward the primary direction of the incoming flow and the conical pump intake nozzle, which avoids accumulations of air, which are harmful in the upper suction area (as opposed to round intake nozzles), the suction behavior is favorably affected with partially emerging propeller blades. Compared to hydrojets with horizontal axis of rotation of the propeller, the actual draft is markedly smaller than the necessary draft.

Due to the suction effect of the relatively flatly sloped propeller not being directed directly toward the bottom and the intake opening being larger (in relation to the propeller diameters of other hydrojets), the shallow water properties and the development of thrust, the wake effect, and the resistance are improved.

To achieve an especially compact design of the hydrojet according to the present invention, it proved to be advantageous for the hydrojet to comprise a housing unit, which can be inserted into the bottom of the boat and is formed from at least four housing sections, which are connected with one another: An intake housing section, which is flush with the bottom, is preferably designed for displacement-type watercraft and is joined concentrically by a tubular pump housing section with

an axis sloped in relation to the horizontal. At an equal slope, a bent housing section, which is used as a housing base with an integrated propeller shaft mount and is preferably formed by a commercially available 90° semicircular bend, but may also have another shape, is attached at the other end of this pump housing section. A discharge housing section, in which a mount of a steerable bottom deflection grid is located, is attached at the other, obliquely downwardly pointing end of the bend.

To ensure optimal incoming flow at the propeller as a requirement for the efficient development of thrust for manoeuvring during standing and at low speed, but also for speeding up to the cruising speed, the intake housing section is designed according to special shape and cross section features, which are best for the different incoming flow conditions (as they are similarly distinguished in suction and feed operation in stationary pumps).

Beginning flatly, the intake housing contour above the intake opening assumes a trapezoidal cross section with rounded corners until the radii of the corners form an arched cross section with a circular radius, in the course of the further rise, which is joined by a conical pump intake nozzle.

Due to the contours of this intake housing section being directed toward the principal direction of travel (i.e., forward travel) and as lateral and oblique incoming flows are also captured in a funnel-like manner, the water is fed optimally to the propeller, which is sloped toward the flow.

The tubular pump housing section, which is arranged between the intake housing section and the pipe bend and is made of an especially corrosion-resistant and wear-resistant material, forms as the

central pump housing an axial-flow pump with at least one propeller and stator blades, which are arranged stationarily after it and convert the swirl energy into kinetic energy and act at the same time as webs for supporting the central bearing hub. An alternative supporting of the bearing hub, e.g., with spokes of a round cross section, etc., is likewise conceivable and included.

5 Depending on the conditions of the watercraft and the drive power needed, mainly electric motors and internal combustion engines, but also hydraulic motors are used for the drive. When electric motors are used, different drive speeds are preset depending on the onboard frequency (e.g., 50 Hz or 60 Hz) and the model of the motor (number of pole pairs). Therefore, it proved to be
7 advantageous if the electric motor can either be attached directly by means of a coaxial housing bell
-10 or axially in parallel and by means of a high-output belt drive and a correspondingly selectable gear reduction above the hydrojet or even on the right-hand side or the left-hand side at the housing unit.

When the hydrojet is to be driven by means of an internal combustion engine, it proved to be particularly advantageous to connect the internal combustion engine with the propeller shaft via a marine gear of the so-called V version with a standard shaft slope angle of, e.g., 10°. As a result, an
15 especially compact installation of the internal combustion engine at the hydrojet is possible. The engine and the gear can be preferably aligned with one another on a common base frame and arranged in a fixed manner, and the base frame is then mounted as an elastically mounted unit on the brackets arranged at the hydrojet. Besides the standard gear reduction variants for adjusting the speed of rotation, the reversing stage of this marine gear can be used to clean the intake protective
20 grid by flushing.

To reach an efficient thrust in case of the predominant use in shallow waters, the intake housing section can be designed in special variants specific for the installation. By making, for example, the intake level of the front intake edge or of a lateral intake edge somewhat higher and/or by varying the slope of the front housing surface or of a lateral housing surface, flat, open areas can be created in the bow area or on the side of a watercraft, so that additional (air-free) water can flow to the propeller directly from the front or from the side (among other things, for example, in pontoon and double-ended ferries with lateral or diagonal jet installation).

The hydrojet according to the present invention can also be used for various types of watercraft and for various purposes, e.g., as a manoeuvring and auxiliary unit and/or as a main drive unit in different positions in the bottom of the watercraft. Mainly watercraft for inland waters, such as freighters, passenger boats and utility boats as well as ferries, landing boats, watercraft used by authorities, and those in which increased requirements are imposed on holding positions, e.g., fire boats, diver boats, surveying and laboratory boats, etc., may be considered. However, the hydrojet according to the present invention may also be used, if designed correspondingly, as a maneuvering unit in coastal and ocean-going vessels.

Further details and advantages of the present invention will appear from the following exemplary embodiments explained on the basis of figures. In the drawings,

Figure 1 shows the longitudinal section through a hydrojet according to the present invention with an electric motor as a coaxial direct drive or in axially parallel arrangement with a belt drive;

Figure 2 shows a bottom view of the hydrojet shown in Figure 1 from the direction designated by II in Figure 1;

Figures 3 and 4 show two sections along the section lines designated by III-III and IV-IV in Figure 2; and

5 Figure 5 shows the cross section of the hydrojet shown in Figure 1 with an internal combustion engine as the drive.

A hydrojet according to the present invention, which can be driven either by means of a coaxially attached electric motor 2 (flange motor) or by means of an electric motor 2' (conventional motor) attached axially in parallel via a belt drive 33 and a corresponding gear reduction with the desired
10 propeller speed or circumferential velocity, is designated by 1 in Figure 1.

The hydrojet 1 comprises a housing unit 3, which can be inserted into the bottom of the boat (not shown) and comprises four housing sections 4-7: An intake housing section 4, which is preferably designed for displacement-type watercraft, is flush with the bottom and is joined concentrically by a tubular pump housing section 5 for accommodating a propeller 10. According to the present
15 invention, the axis of rotation 9 of the propeller and hence also the propeller shaft 11 are arranged at a slope angle α of preferably 28° in relation to a horizontal base, which is formed by the bottom plate 20 of the housing unit 3.

A pipe bend 6, which is used to mount the propeller shaft 11 as a housing base and may be a

commercially available 90° semicircular bend, is attached to the pump housing section 5 in the direction of the sloped axis of rotation 9 of the propeller. A discharge housing section 7, which is flush with the bottom, is attached with a discharge opening 15 at the other, obliquely downwardly pointing end of the arch end of bend 14 of the pipe bend 6, a pivotable bottom deflecting grid 16 for steering the water jet being arranged in the discharge opening 15.

To pass through, mount and seal the steering shaft 17 and the propeller shaft 11, support studs 18, 19, which are concentric with the respective shaft axes, are arranged on the semicircular bend 6.

The water-carrying housing sections 4-7 and a bottom plate 20 connecting the intake and discharge openings 13 and 15 are connected with one another by a prefabricated housing unit 3, which can be completed with corresponding motor brackets 37 and anchor brackets 45, 46 for the installation of the desired drive motor 2, 2' or 40.

Furthermore, the housing unit 3 may be made with an inspection cover above the lowest-draft water line (not shown), which makes possible the inspection and cleaning of the intake area from the engine room.

Due to the contours of the intake housing section 4 being directed in the principal direction of travel (i.e., forward travel), the water is fed optimally to the propeller 10, which is sloped toward the flow. Oblique and lateral incoming flows are also captured by means of the lateral surfaces of the intake housing section 4, which are extended obliquely outwardly according to Figures 3 and 4.

The contours of the intake housing section 4 are selected here to be such that the sections of the tunnel cross sections 21, 22 in Figures 3 and 4 increase continuously in terms of their height and their upper corner radii until they form a tunnel with a circular arch, to which a conical pump intake nozzle 23 is added. The contour of the pump intake nozzle 23 decreases under the axis of rotation 9 of the propeller until it passes over into the bottom plate 20 in the downward direction. Alternative embodiments to this are conceivable and included.

A protective grid 24 against foreign bodies of a harmful size, which is either mounted permanently or is arranged pivotably to shake off foreign bodies that may be present and grants easy access to the intake area and the propeller 10 for inspection, maintenance and in case of repair, is located in the area of the intake opening 13 of the intake housing section 4.

The tubular pump housing section 5 arranged between the intake housing section 4 and the pipe bend 6 forms the pump housing with a narrow radial gap around at least one propeller 10 and the impeller pump 8 together with the guide vanes 26 arranged behind it, which convert the swirl energy into kinetic energy and at the same time support the bearing hub 27. An alternative hub support with, e.g., nonprofiled spokes (instead of 26) is conceivable and included. The propeller-like bearing hub 27 preferably contains a usual water-lubricated propeller shaft gliding surface bearing 39.

The upper propeller shaft bearing 28 sealed on both sides is provided as a grease-lubricated rolling bearing for absorbing axial and radial loads and is arranged in the support stud 19 attached on the pipe bend 6.

A bearing hub 30 supported via webs 29 is likewise arranged in the discharge housing section 7 for receiving and mounting the bottom deflection grid 16, at least two webs 29 being arranged above the front half of the bottom such that they facilitate the guiding of the flow to and through the bottom deflection grid 16 there.

5 For steering the bottom deflecting grid 16 all round, the vertical steering shaft 17 is preferably mounted in the support stud 18 of the housing unit 3, at the bottom in a water-lubricated gliding surface bearing 31 and at the top in a grease-lubricated rolling bearing 32, which is sealed on both sides and can absorb axial and radial loads. A driving hub 33 for the steering drive (not shown) and a small power take-off hub 34 for the optical and electric thrust direction display (not shown) are
10 arranged on the steering shaft 17.

The electric motor 2 (flange motor) is connected with the propeller shaft 11 via an elastic shaft coupling 35 and is mounted on the support stud 19 of the housing unit 3 via a coaxial housing bell 36. The use of an electric motor 2' (conventional motor) and of a corresponding high-performance belt drive 38 to drive the propeller shaft 11 make it possible to adapt frequency-dependent motor
15 speeds to a uniform propeller speed or to a certain circumferential velocity. Depending on the given space conditions, the electric motors 2, 2' can be installed optionally in front of the propeller shaft 11 or by means of an axially parallel motor bracket 37 above or also laterally at the housing unit 3 of the hydrojet 1 to form a ready-to-operate drive unit.

20 An internal combustion engine 40 is provided for driving the hydrojet 1 in the exemplary embodiment of the present invention shown in Figure 5. To achieve a compact and advantageous

arrangement of the drive components, the internal combustion engine 40 is mounted with the rotationally elastic motor coupling 41 attached thereto, together with a commercially available marine gear 42, preferably of a V version (i.e., the horizontal drive axis and the sloped power take-off axis form a "horizontal V") on a common base frame 43 and positioned such that a W
5 arrangement with two equal bending angles of a permissible size is obtained for the cardan shaft 44 to be connected.

The base frame 43 is aligned with the propeller shaft 11 on anchor brackets 45, 46, which are arranged at the housing unit 3, at least at four points via rubber-metal damping elements 47 and mounted elastically. Load-dependent displacements and spring incursions are compensated by the
10 elastic shaft coupling 48 in a double cardanic design. Moreover, the rubber-metal damping elements 47 and the two elastic elements of the coupling 48 are used at the same time to effectively damp the transmission of vibrations and structure-borne noise to the hydrojet 1 and thus to the hull.

The present invention is, of course, not limited to the above-described exemplary embodiments.

Thus, the hydrojet may, in principle, also be designed with a two-stage axial-flow pump (pump with
15 a propeller shaft 11 and two propellers 10 with guide vanes 26 located between them) instead of with the one-stage axial-flow pump shown in Figures 1-5.

Besides, the hydrojet 1 may also be designed with a variable-pitch blade impeller pump, instead of with a fixed-pitch impeller pump, in which case the propeller shaft 11 is hollow in order to pass through, e.g., an actuating rod or lines for adjusting the propeller blades respectively (the pitch of
20 the respective propeller blades). In case of a drive by means of an electric motor installed with

parallel axis, the means for adjusting the pitch can be mounted in front of the support stud 19 at the hydrojet 1. In case of an internal combustion engine as the drive motor, it is possible to pass, e.g., an extended actuating rod through the shaft coupling 48 and the hollow power take-off shaft of the marine gear 42, so that the adjusting means can be attached to the marine gear 42, as usual, on the outside.

List of Reference Numbers

	1	Hydrojet
	2, 2'	Electric motor, drive
5	3	Housing unit
	4	Intake housing section, housing section
	5	Pump housing section, housing section
	6	Pipe bend, bent housing section
	7	Discharge housing section, housing section
10	8	Axial-flow pump, pump
	9	Axis of rotation of propeller
	10	Propeller
	11	Propeller shaft
	12	Base
15	13	Intake opening
	14	End of bend
	15	Discharge opening
	16	Bottom deflecting grid
	17	Steering shaft
20	18	Support stud (steering shaft)

	19	Support stud (propeller shaft)
	20	Bottom plate
	21	Tunnel cross section
	22	Arched tunnel cross section
5	23	Pump intake nozzle
	24	Protective grid
	25	Stator
	26	Guide vane
	27	Bearing hub
10	28	Sealed rolling bearing (propeller shaft)
	29	Web
	30	Bearing hub
	31	Gliding surface bearing
	32	Sealed rolling bearing (steering shaft)
15	33	Drive hub
	34	Power take-off hub
	35	Elastic shaft coupling
	36	Housing bell
	37	Motor bracket
20	38	Belt drive
	39	Propeller shaft gliding surface bearing
	40	Internal combustion engine, motor, drive
	41	Rotationally elastic motor coupling

	42	Marine gear, gear
	43	Base frame
	44	Cardan shaft
	45	Anchor bracket
5	46	Anchor bracket
	47	Rubber-metal damping element
	48	Elastic double cardan shaft coupling, coupling
	49	Gear bracket